

Dual and Single Precision, 17 MHz, Low Noise, CMOS Input Amplifiers with Enable

Check for Samples: [SM73304](#), [SM73305](#)

FEATURES

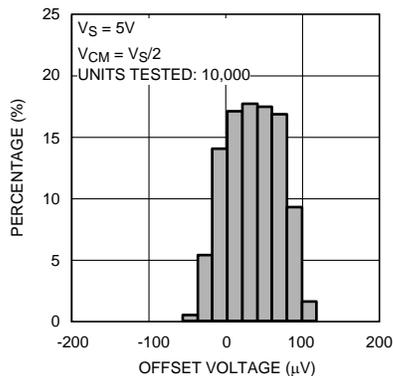
Unless Otherwise Noted, Typical Values at $V_S = 5V$.

- Renewable Energy Grade
- Input Offset Voltage $\pm 150 \mu V$ (max)
- Input Bias Current 100 fA
- Input Voltage Noise $5.8 \text{ nV}/\sqrt{\text{Hz}}$
- Gain Bandwidth Product 17 MHz
- Supply Current (SM73305) 1.15 mA
- Supply Current (SM73304) 1.30 mA
- Supply Voltage Range 1.8V to 5.5V
- THD+N @ $f = 1 \text{ kHz}$ 0.001%
- Operating Temperature Range -40°C to 125°C
- Rail-to-Rail Output Swing
- Space Saving SOT Package (SM73305)
- 10-Pin VSSOP Package (SM73304)

APPLICATIONS

- Photovoltaic Electronics
- Active Filters and Buffers
- Sensor Interface Applications
- Transimpedance Amplifiers

Typical Performance


Figure 1. Offset Voltage Distribution

DESCRIPTION

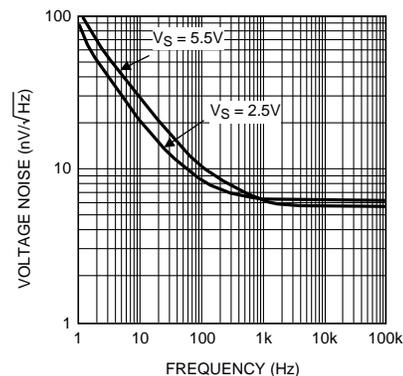
The SM73304/SM73305 are dual and single low noise, low offset, CMOS input, rail-to-rail output precision amplifiers with a high gain bandwidth product and an enable pin. The SM73304/SM73305 are ideal for a variety of instrumentation applications.

Utilizing a CMOS input stage, the SM73304/SM73305 achieve an input bias current of 100 fA, an input referred voltage noise of $5.8 \text{ nV}/\sqrt{\text{Hz}}$, and an input offset voltage of less than $\pm 150 \mu V$. These features make the SM73304/SM73305 superior choices for precision applications.

Consuming only 1.15 mA of supply current, the SM73305 offers a high gain bandwidth product of 17 MHz, enabling accurate amplification at high closed loop gains.

The SM73304/SM73305 have a supply voltage range of 1.8V to 5.5V, which makes these ideal choices for portable low power applications with low supply voltage requirements. In order to reduce the already low power consumption the SM73304/SM73305 have an enable function. Once in shutdown, the SM73304/SM73305 draw only 140 nA of supply current.

The SM73304/SM73305 are built with National's advanced VIP50 process technology. The SM73305 is offered in a 6-pin SOT package and the SM73304 is offered in a 10-pin VSSOP.


Figure 2. Input Referred Voltage Noise


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These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

Absolute Maximum Ratings ⁽¹⁾⁽²⁾

ESD Tolerance ⁽³⁾	Human Body Model	2000V
	Machine Model	200V
	Charge-Device Model	1000V
V_{IN} Differential		±0.3V
Supply Voltage ($V_S = V^+ - V^-$)		6.0V
Voltage on Input/Output Pins		$V^+ +0.3V, V^- -0.3V$
Storage Temperature Range		-65°C to 150°C
Junction Temperature ⁽⁴⁾		+150°C
Soldering Information	Infrared or Convection (20 sec)	235°C
	Wave Soldering Lead Temp. (10 sec)	260°C

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not guaranteed. For guaranteed specifications and the test conditions, see the Electrical Characteristics Tables.
- (2) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/ Distributors for availability and specifications.
- (3) Human Body Model, applicable std. MIL-STD-883, Method 3015.7. Machine Model, applicable std. JESD22-A115-A (ESD MM std. of JEDEC) Field-Induced Charge-Device Model, applicable std. JESD22-C101-C (ESD FICDM std. of JEDEC).
- (4) The maximum power dissipation is a function of $T_{J(MAX)}$, θ_{JA} . The maximum allowable power dissipation at any ambient temperature is $P_D = (T_{J(MAX)} - T_A)/\theta_{JA}$. All numbers apply for packages soldered directly onto a PC Board.

Operating Ratings ⁽¹⁾

Temperature Range ⁽²⁾		-40°C to 125°C
Supply Voltage ($V_S = V^+ - V^-$)	$0^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$	1.8V to 5.5V
	$-40^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$	2.0V to 5.5V
Package Thermal Resistance (θ_{JA}) ⁽²⁾	6-Pin SOT	170°C/W
	10-Pin VSSOP	236°C/W

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not guaranteed. For guaranteed specifications and the test conditions, see the Electrical Characteristics Tables.
- (2) The maximum power dissipation is a function of $T_{J(MAX)}$, θ_{JA} . The maximum allowable power dissipation at any ambient temperature is $P_D = (T_{J(MAX)} - T_A)/\theta_{JA}$. All numbers apply for packages soldered directly onto a PC Board.

2.5V Electrical Characteristics

Unless otherwise specified, all limits are guaranteed for $T_A = 25^\circ\text{C}$, $V^+ = 2.5\text{V}$, $V^- = 0\text{V}$, $V_O = V_{CM} = V^+/2$, $V_{EN} = V^+$. **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min (1)	Typ (2)	Max (1)	Units
V_{OS}	Input Offset Voltage			± 20	± 180 ± 480	μV
$TC V_{OS}$	Input Offset Voltage Temperature Drift (3) (4)	SM73305		-1	± 4	$\mu\text{V}/^\circ\text{C}$
		SM73304		-1.75		
I_B	Input Bias Current	$V_{CM} = 1.0\text{V}$ (5) (4)	$-40^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$	0.05	1 25	pA
			$-40^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$	0.05	1 100	
I_{OS}	Input Offset Current	$V_{CM} = 1.0\text{V}$ (4)		0.006	0.5 50	pA
CMRR	Common Mode Rejection Ratio	$0\text{V} \leq V_{CM} \leq 1.4\text{V}$	83 80	100		dB
PSRR	Power Supply Rejection Ratio	$2.0\text{V} \leq V^+ \leq 5.5\text{V}$ $V^- = 0\text{V}$, $V_{CM} = 0$	85 80	100		dB
		$1.8\text{V} \leq V^+ \leq 5.5\text{V}$ $V^- = 0\text{V}$, $V_{CM} = 0$	85	98		
CMVR	Common Mode Voltage Range	CMRR $\geq 80\text{ dB}$ CMRR $\geq 78\text{ dB}$	-0.3 -0.3		1.5 1.5	V
A_{VOL}	Open Loop Voltage Gain	SM73305, $V_O = 0.15$ to 2.2V $R_L = 2\text{ k}\Omega$ to $V^+/2$	88 82	98		dB
		SM73304, $V_O = 0.15$ to 2.2V $R_L = 2\text{ k}\Omega$ to $V^+/2$	84 80	92		
		SM73305, $V_O = 0.15$ to 2.2V $R_L = 10\text{ k}\Omega$ to $V^+/2$	92 88	110		
		SM73304, $V_O = 0.15$ to 2.2V $R_L = 10\text{ k}\Omega$ to $V^+/2$	90 86	95		
V_{OUT}	Output Voltage Swing High	$R_L = 2\text{ k}\Omega$ to $V^+/2$		25	70 77	mV from either rail
		$R_L = 10\text{ k}\Omega$ to $V^+/2$		20	60 66	
	Output Voltage Swing Low	$R_L = 2\text{ k}\Omega$ to $V^+/2$		30	70 73	
		$R_L = 10\text{ k}\Omega$ to $V^+/2$		15	60 62	
I_{OUT}	Output Current	Sourcing to V^- $V_{IN} = 200\text{ mV}$ (6)	36 30	52		mA
		Sinking to V^+ $V_{IN} = -200\text{ mV}$ (6)	7.5 5.0	15		
I_S	Supply Current	SM73305 Enable Mode $V_{EN} \geq 2.1$		0.95	1.30 1.65	mA
		SM73304 (per channel) Enable Mode $V_{EN} \geq 2.1$		1.10	1.50 1.85	
		Shutdown Mode (per channel) $V_{EN} \leq 0.4$		0.03	1 4	μA

- (1) Limits are 100% production tested at 25°C . Limits over the operating temperature range are guaranteed through correlations using the Statistical Quality Control (SQC) method.
- (2) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not guaranteed on shipped production material.
- (3) Offset voltage average drift is determined by dividing the change in V_{OS} at the temperature extremes by the total temperature change.
- (4) This parameter is guaranteed by design and/or characterization and is not tested in production.
- (5) Positive current corresponds to current flowing into the device.
- (6) The short circuit test is a momentary open loop test.

2.5V Electrical Characteristics (continued)

Unless otherwise specified, all limits are guaranteed for $T_A = 25^\circ\text{C}$, $V^+ = 2.5\text{V}$, $V^- = 0\text{V}$, $V_O = V_{CM} = V^+/2$, $V_{EN} = V^+$. **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min (1)	Typ (2)	Max (1)	Units
SR	Slew Rate	$A_V = +1$, Rising (10% to 90%)		8.3		V/ μs
		$A_V = +1$, Falling (90% to 10%)		10.3		
GBW	Gain Bandwidth			14		MHz
e_n	Input Referred Voltage Noise Density	$f = 400\text{ Hz}$		6.8		nV/ $\sqrt{\text{Hz}}$
		$f = 1\text{ kHz}$		5.8		
i_n	Input Referred Current Noise Density	$f = 1\text{ kHz}$		0.01		pA/ $\sqrt{\text{Hz}}$
t_{on}	Turn-on Time			140		ns
t_{off}	Turn-off Time			1000		ns
V_{EN}	Enable Pin Voltage Range	Enable Mode	2.1	2 - 2.5		V
		Shutdown Mode		0 - 0.5	0.4	
I_{EN}	Enable Pin Input Current	$V_{EN} = 2.5\text{V}$ (5)		1.5	3.0	μA
		$V_{EN} = 0\text{V}$ (5)		0.003	0.1	
THD+N	Total Harmonic Distortion + Noise	$f = 1\text{ kHz}$, $A_V = 1$, $R_L = 100\text{ k}\Omega$ $V_O = 0.9 V_{PP}$		0.003		%
		$f = 1\text{ kHz}$, $A_V = 1$, $R_L = 600\Omega$ $V_O = 0.9 V_{PP}$		0.004		

5V Electrical Characteristics

Unless otherwise specified, all limits are guaranteed for $T_A = 25^\circ\text{C}$, $V^+ = 5\text{V}$, $V^- = 0\text{V}$, $V_{CM} = V^+/2$, $V_{EN} = V^+$. **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min (1)	Typ (2)	Max (1)	Units
V_{OS}	Input Offset Voltage			± 10	± 150 ± 450	μV
TC V_{OS}	Input Offset Voltage Temperature Drift (3) (4)	SM73305	-1.75	-1	± 4	$\mu\text{V}/^\circ\text{C}$
		SM73304				
I_B	Input Bias Current	$V_{CM} = 2.0\text{V}$ (5) (4)	$-40^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$	0.1	1 25	pA
			$-40^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$		0.1	
I_{OS}	Input Offset Current	$V_{CM} = 2.0\text{V}$ (4)		0.01	0.5 50	pA
CMRR	Common Mode Rejection Ratio	$0\text{V} \leq V_{CM} \leq 3.7\text{V}$	85 82	100		dB
PSRR	Power Supply Rejection Ratio	$2.0\text{V} \leq V^+ \leq 5.5\text{V}$ $V^- = 0\text{V}$, $V_{CM} = 0$	85 80	100		dB
		$1.8\text{V} \leq V^+ \leq 5.5\text{V}$ $V^- = 0\text{V}$, $V_{CM} = 0$	85	98		
CMVR	Common Mode Voltage Range	CMRR $\geq 80\text{ dB}$ CMRR $\geq 78\text{ dB}$	-0.3 -0.3		4 4	V

- (1) Limits are 100% production tested at 25°C . Limits over the operating temperature range are guaranteed through correlations using the Statistical Quality Control (SQC) method.
- (2) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not guaranteed on shipped production material.
- (3) Offset voltage average drift is determined by dividing the change in V_{OS} at the temperature extremes by the total temperature change.
- (4) This parameter is guaranteed by design and/or characterization and is not tested in production.
- (5) Positive current corresponds to current flowing into the device.

5V Electrical Characteristics (continued)

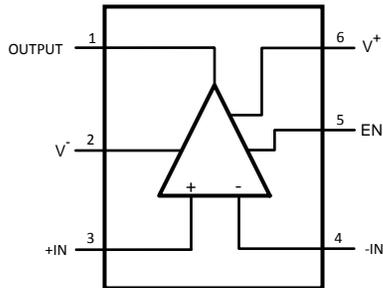
Unless otherwise specified, all limits are guaranteed for $T_A = 25^\circ\text{C}$, $V^+ = 5\text{V}$, $V^- = 0\text{V}$, $V_{\text{CM}} = V^+/2$, $V_{\text{EN}} = V^+$. **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min (1)	Typ (2)	Max (1)	Units	
A_{VOL}	Open Loop Voltage Gain	SM73305, $V_O = 0.3$ to 4.7V $R_L = 2\text{ k}\Omega$ to $V^+/2$	88 82	107		dB	
		SM73304, $V_O = 0.3$ to 4.7V $R_L = 2\text{ k}\Omega$ to $V^+/2$	84 80	90			
		SM73305, $V_O = 0.3$ to 4.7V $R_L = 10\text{ k}\Omega$ to $V^+/2$	92 88	110			
		SM73304, $V_O = 0.3$ to 4.7V $R_L = 10\text{ k}\Omega$ to $V^+/2$	90 86	95			
V_{OUT}	Output Voltage Swing High	$R_L = 2\text{ k}\Omega$ to $V^+/2$		32	70 77	mV from either rail	
		$R_L = 10\text{ k}\Omega$ to $V^+/2$		22	60 66		
	Output Voltage Swing Low	$R_L = 2\text{ k}\Omega$ to $V^+/2$ (SM73305)		42	70 73		
		$R_L = 2\text{ k}\Omega$ to $V^+/2$ (SM73304)		50	75 78		
		$R_L = 10\text{ k}\Omega$ to $V^+/2$		20	60 62		
		I_{OUT}	Output Current	Sourcing to V^- $V_{\text{IN}} = 200\text{ mV}$ (6)	46 38	66	mA
				Sinking to V^+ $V_{\text{IN}} = -200\text{ mV}$ (6)	10.5 6.5	23	
I_S	Supply Current	SM73305 Enable Mode $V_{\text{EN}} \geq 4.6$		1.15	1.40 1.75	mA	
		SM73304 (per channel) Enable Mode $V_{\text{EN}} \geq 4.6$		1.30	1.70 2.05		
		Shutdown Mode $V_{\text{EN}} \leq 0.4$ (per channel)		0.14	1 4	μA	
SR	Slew Rate	$A_V = +1$, Rising (10% to 90%)	6.0	9.5		$\text{V}/\mu\text{s}$	
		$A_V = +1$, Falling (90% to 10%)	7.5	11.5			
GBW	Gain Bandwidth			17		MHz	
e_n	Input Referred Voltage Noise Density	$f = 400\text{ Hz}$		7.0		$\text{nV}/\sqrt{\text{Hz}}$	
		$f = 1\text{ kHz}$		5.8			
i_n	Input Referred Current Noise Density	$f = 1\text{ kHz}$		0.01		$\text{pA}/\sqrt{\text{Hz}}$	
t_{on}	Turn-on Time			110		ns	
t_{off}	Turn-off Time			800		ns	
V_{EN}	Enable Pin Voltage Range	Enable Mode	4.6	4.5 – 5		V	
		Shutdown Mode		0 – 0.5	0.4		
I_{EN}	Enable Pin Input Current	$V_{\text{EN}} = 5\text{V}$ (7)		5.6	10	μA	
		$V_{\text{EN}} = 0\text{V}$ (7)		0.005	0.2		
THD+N	Total Harmonic Distortion + Noise	$f = 1\text{ kHz}$, $A_V = 1$, $R_L = 100\text{ k}\Omega$ $V_O = 4\text{ V}_{\text{PP}}$		0.001		%	
		$f = 1\text{ kHz}$, $A_V = 1$, $R_L = 600\Omega$ $V_O = 4\text{ V}_{\text{PP}}$		0.004			

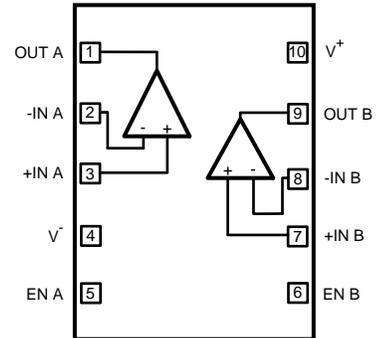
(6) The short circuit test is a momentary open loop test.

(7) Positive current corresponds to current flowing into the device.

Connection Diagram



**Figure 3. 6-Pin SOT
Package Number DDC0006A
Top View**



**Figure 4. 10-Pin VSSOP
Package Number DGS0010A
Top View**

Typical Performance Characteristics

Unless otherwise noted: $T_A = 25^\circ\text{C}$, $V_S = 5\text{V}$, $V_{CM} = V_S/2$, $V_{EN} = V^+$.

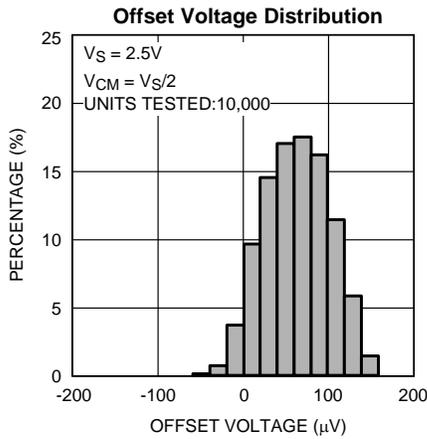


Figure 5.

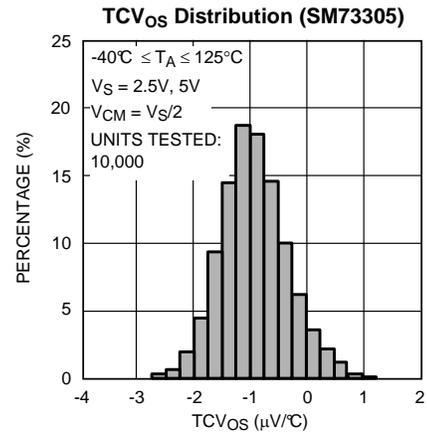


Figure 6.

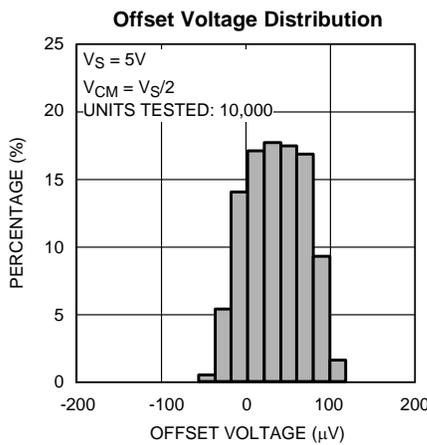


Figure 7.

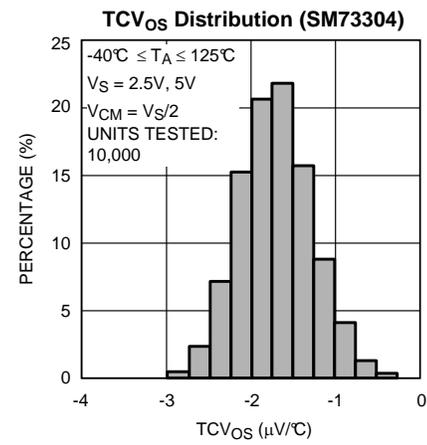


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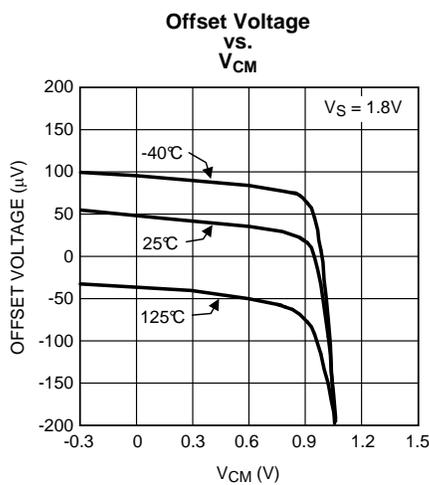


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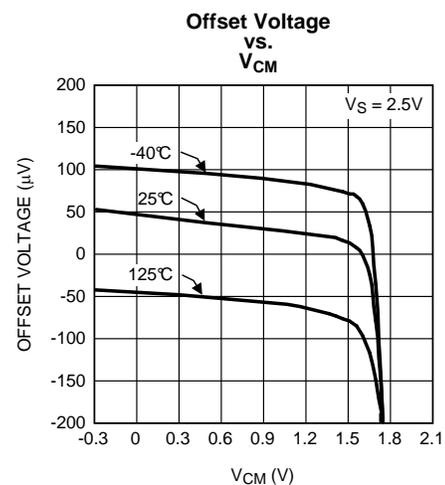


Figure 10.

Typical Performance Characteristics (continued)

Unless otherwise noted: $T_A = 25^\circ\text{C}$, $V_S = 5\text{V}$, $V_{CM} = V_S/2$, $V_{EN} = V^+$.

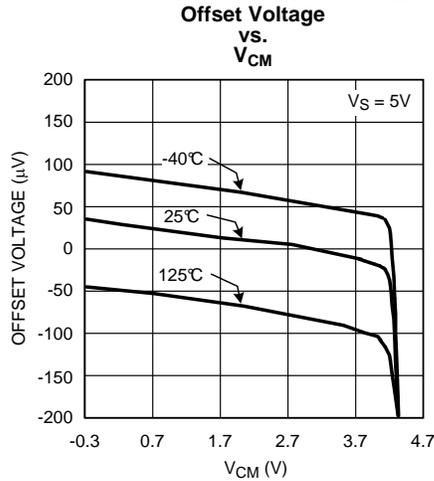


Figure 11.

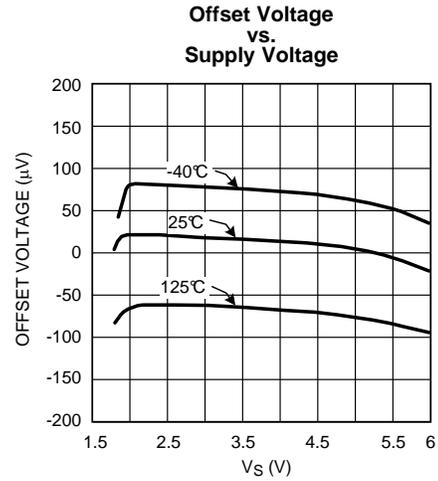


Figure 12.

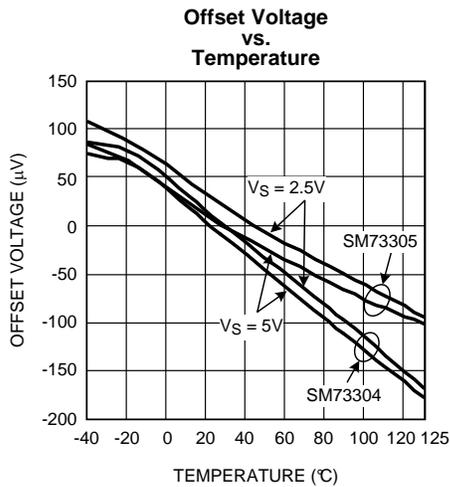


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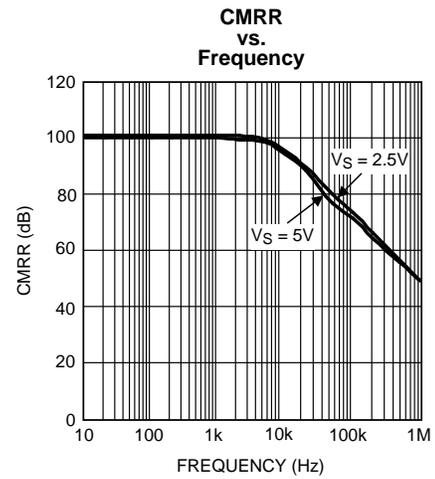


Figure 14.

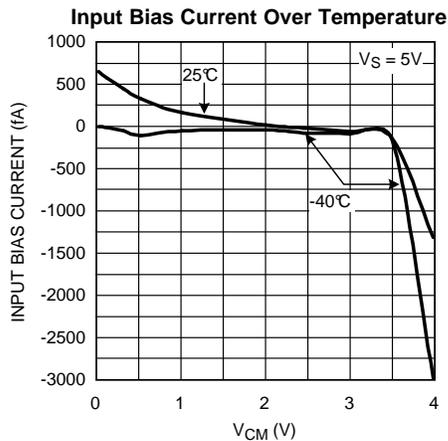


Figure 15.

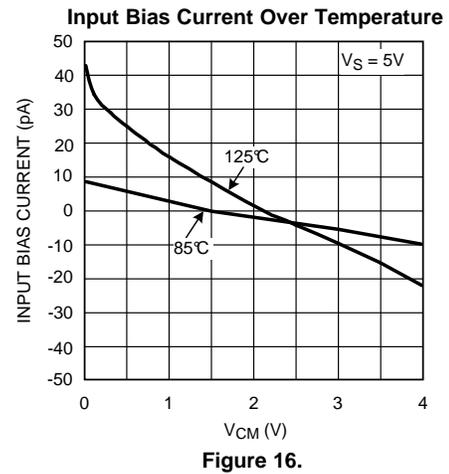


Figure 16.

Typical Performance Characteristics (continued)

Unless otherwise noted: $T_A = 25^\circ\text{C}$, $V_S = 5\text{V}$, $V_{CM} = V_S/2$, $V_{EN} = V^+$.

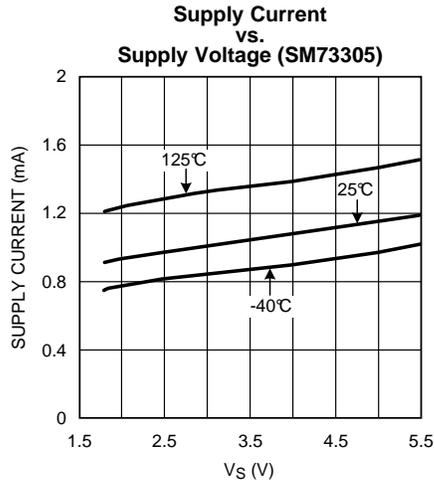


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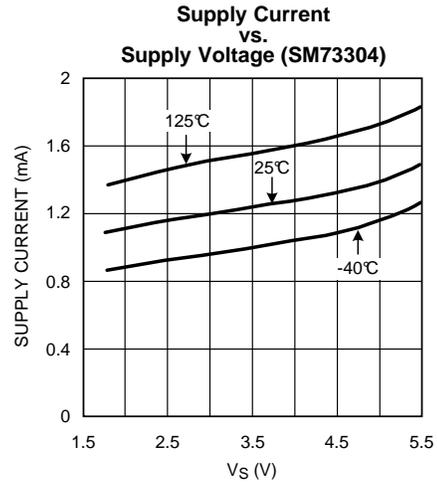


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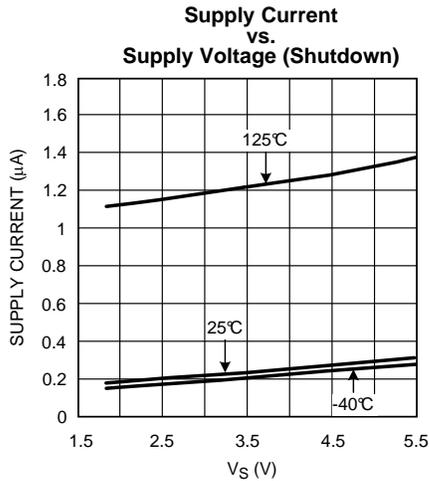


Figure 19.

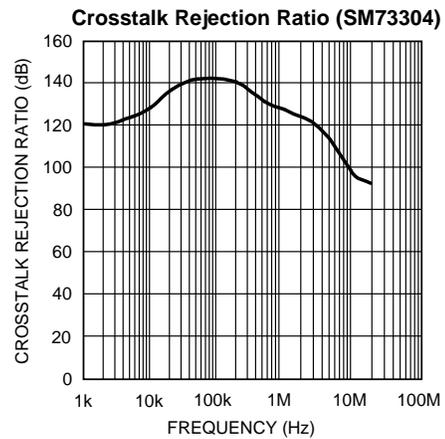


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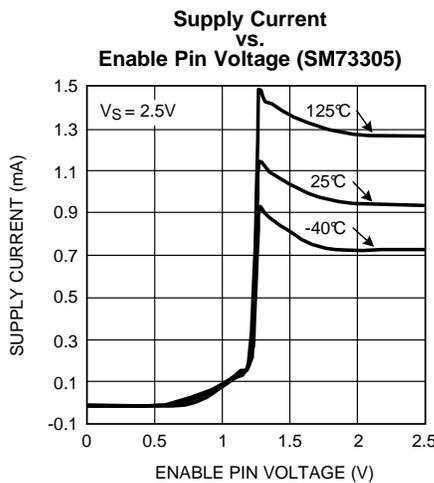


Figure 21.

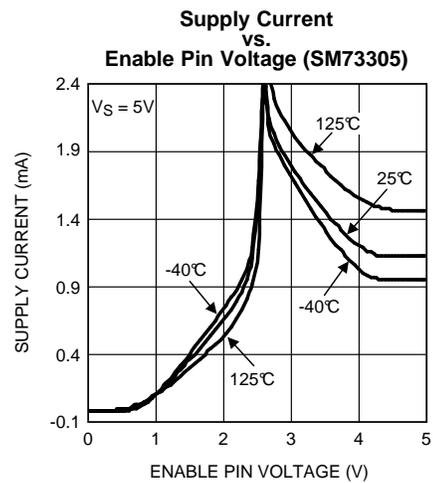


Figure 22.

Typical Performance Characteristics (continued)

Unless otherwise noted: $T_A = 25^\circ\text{C}$, $V_S = 5\text{V}$, $V_{CM} = V_S/2$, $V_{EN} = V^+$.

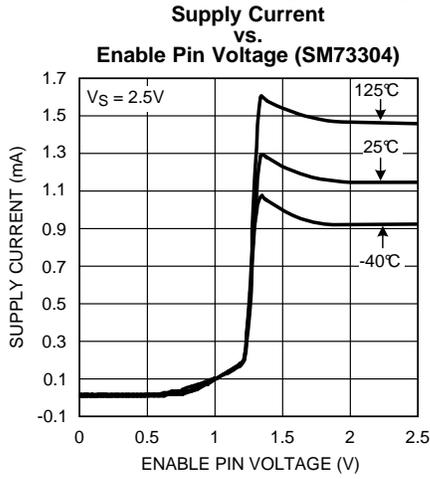


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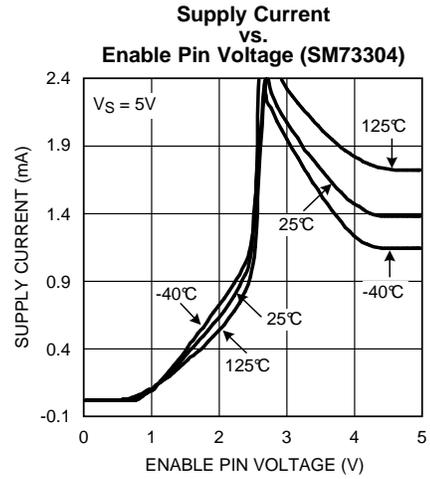


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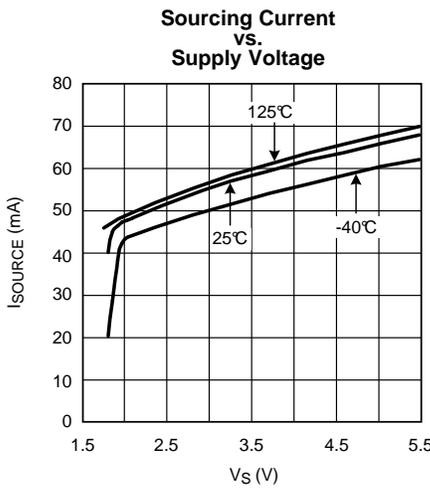


Figure 25.

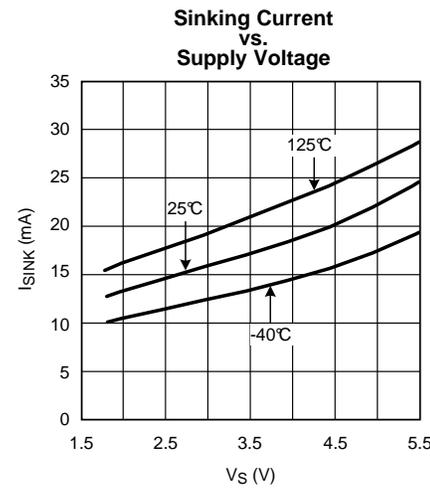


Figure 26.

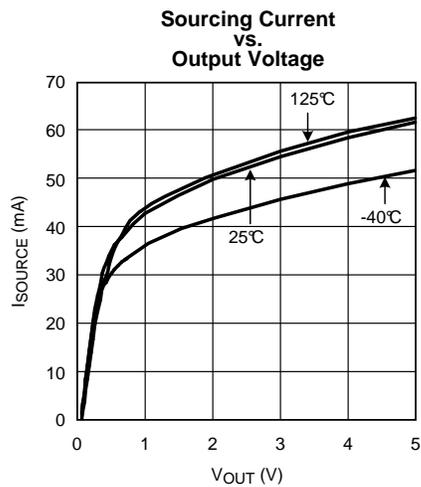


Figure 27.

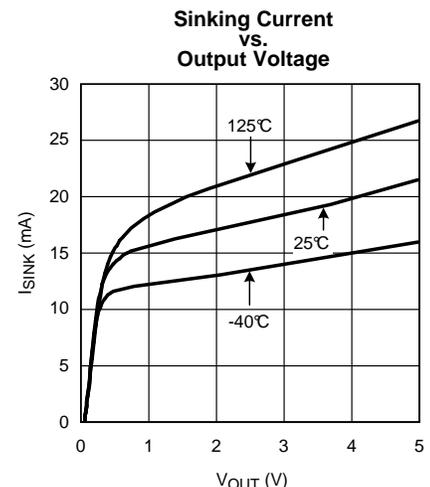


Figure 28.

Typical Performance Characteristics (continued)

Unless otherwise noted: $T_A = 25^\circ\text{C}$, $V_S = 5\text{V}$, $V_{CM} = V_S/2$, $V_{EN} = V^+$.

Output Swing High vs. Supply Voltage

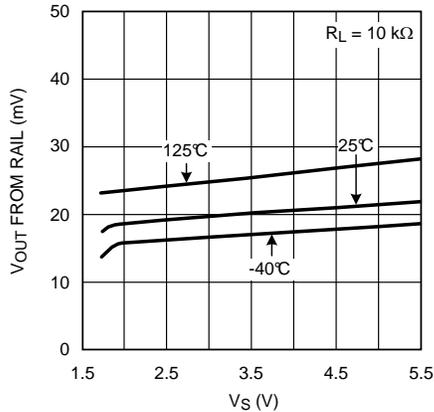


Figure 29.

Output Swing Low vs. Supply Voltage

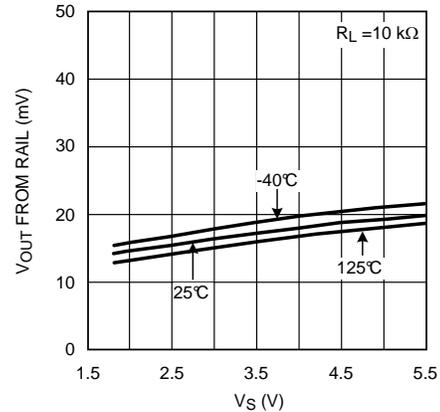


Figure 30.

Output Swing High vs. Supply Voltage

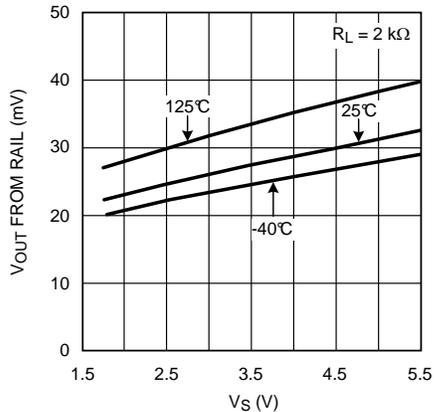


Figure 31.

Output Swing Low vs. Supply Voltage

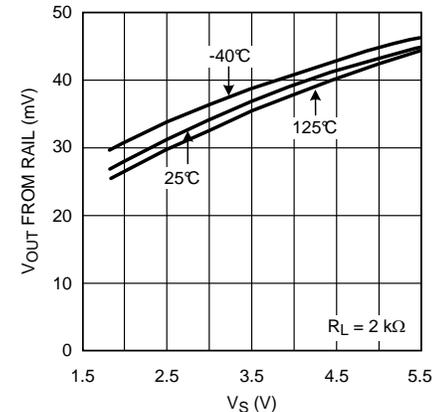


Figure 32.

Output Swing High vs. Supply Voltage

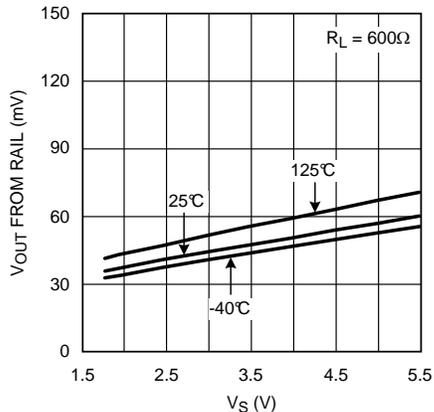


Figure 33.

Output Swing Low vs. Supply Voltage

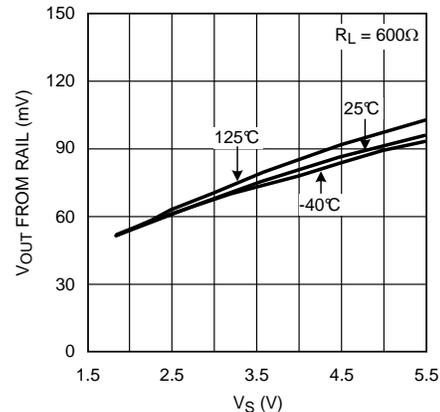


Figure 34.

Typical Performance Characteristics (continued)

Unless otherwise noted: $T_A = 25^\circ\text{C}$, $V_S = 5\text{V}$, $V_{CM} = V_S/2$, $V_{EN} = V^+$.

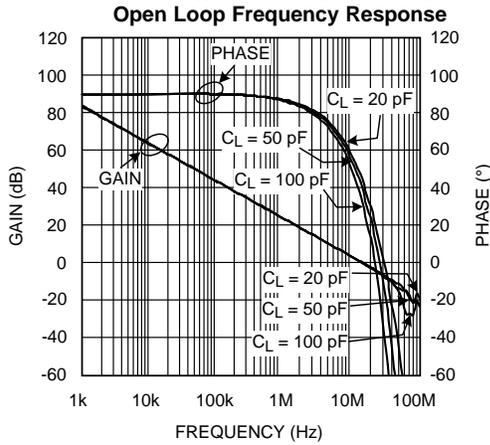


Figure 35.

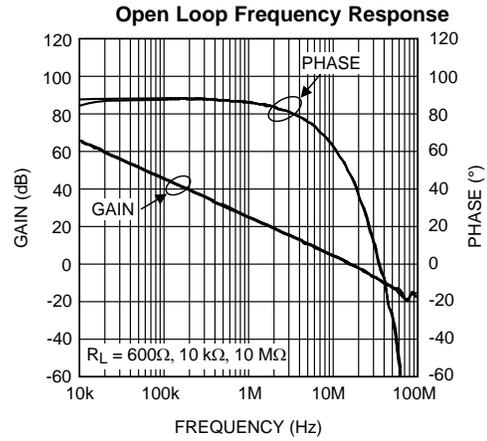


Figure 36.

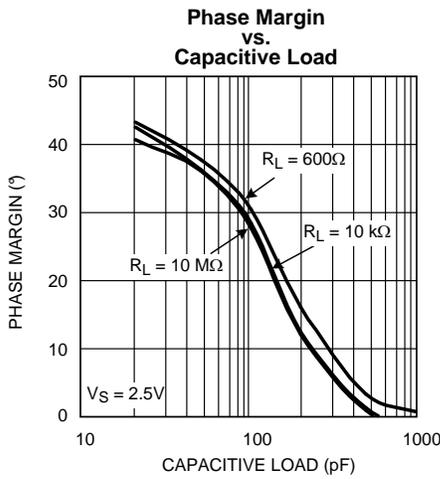


Figure 37.

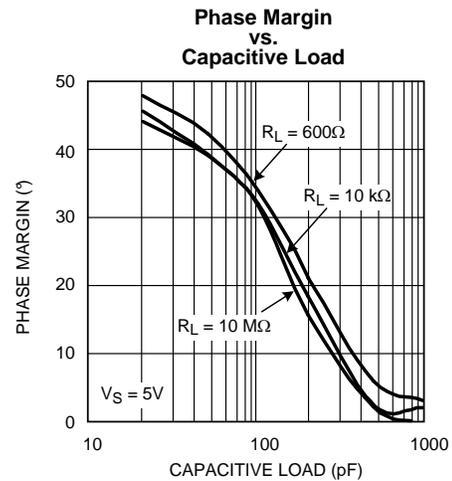


Figure 38.

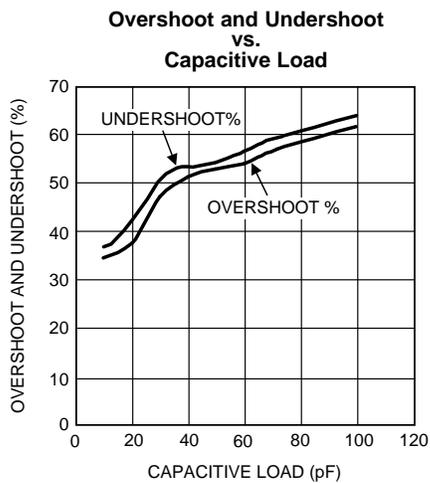


Figure 39.

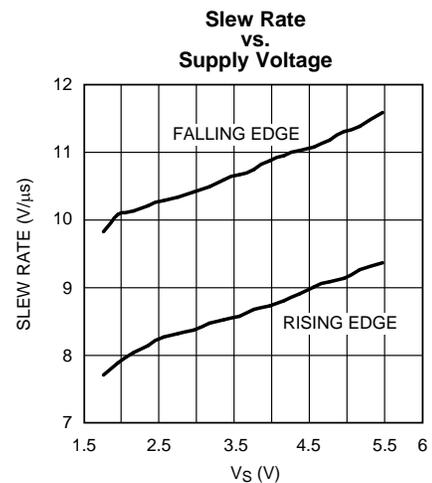


Figure 40.

Typical Performance Characteristics (continued)

Unless otherwise noted: $T_A = 25^\circ\text{C}$, $V_S = 5\text{V}$, $V_{CM} = V_S/2$, $V_{EN} = V^+$.

Small Signal Step Response

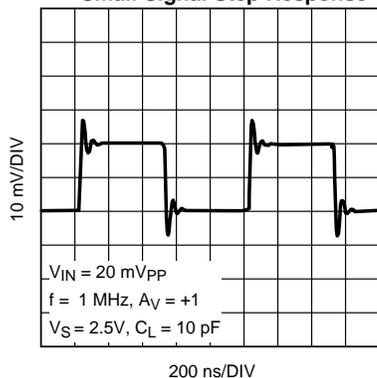


Figure 41.

Large Signal Step Response

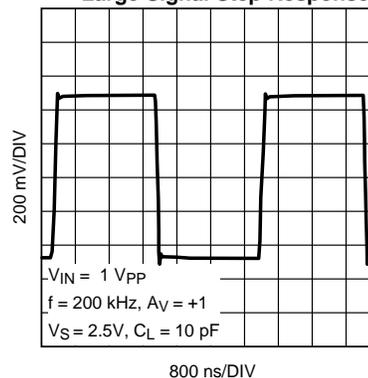


Figure 42.

Small Signal Step Response

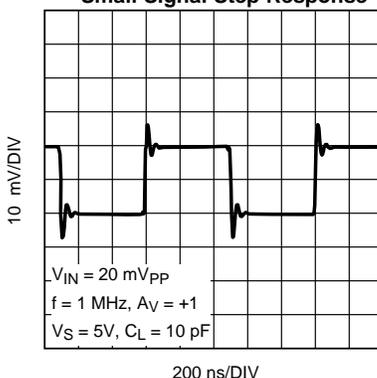


Figure 43.

Large Signal Step Response

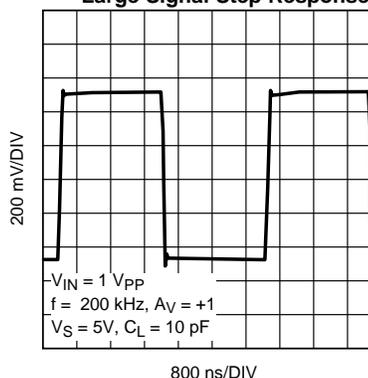


Figure 44.

THD+N vs. Output Voltage

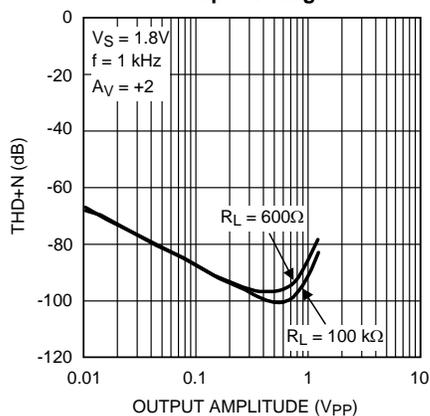


Figure 45.

THD+N vs. Output Voltage

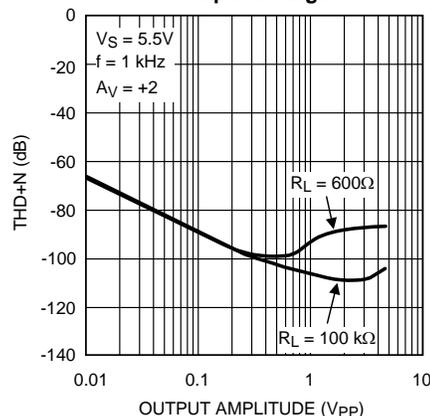


Figure 46.

Typical Performance Characteristics (continued)

Unless otherwise noted: $T_A = 25^\circ\text{C}$, $V_S = 5\text{V}$, $V_{CM} = V_S/2$, $V_{EN} = V^+$.

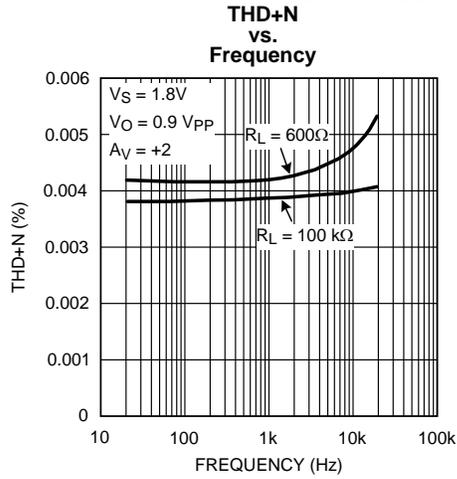


Figure 47.

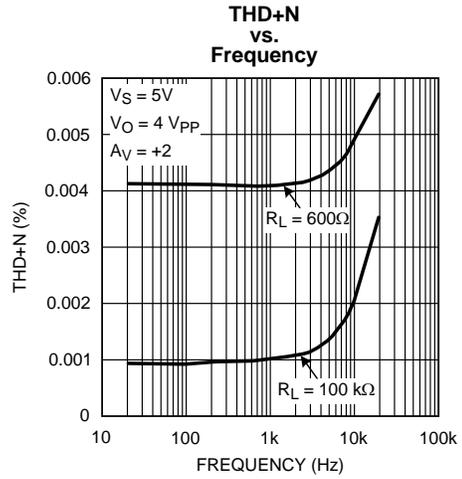


Figure 48.

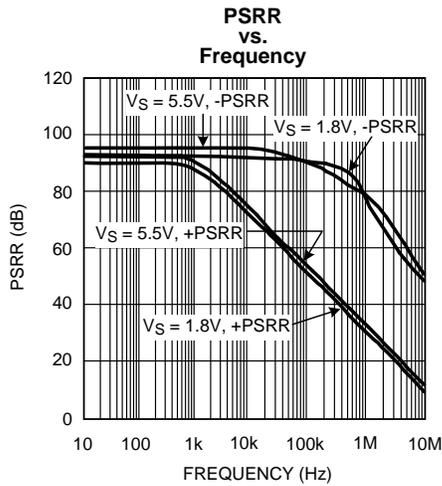


Figure 49.

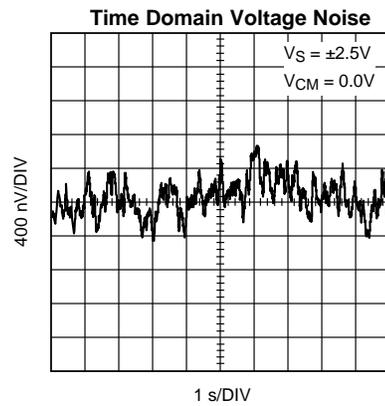


Figure 50.

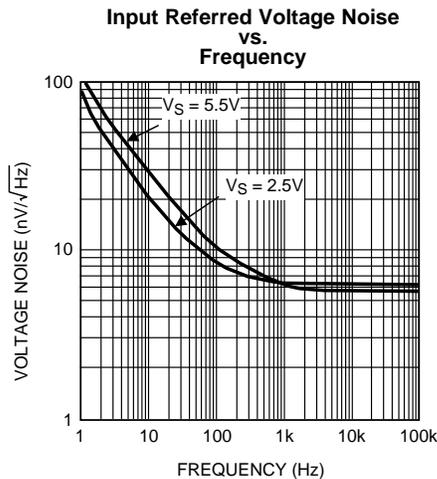


Figure 51.

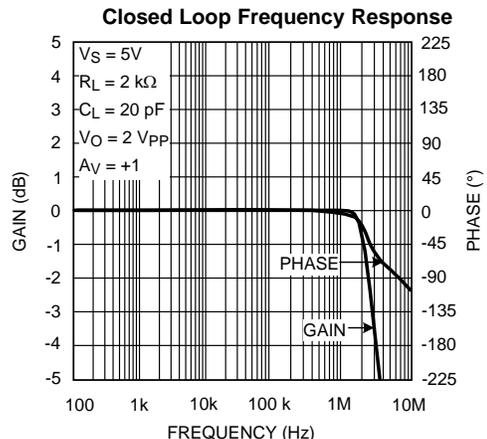


Figure 52.

Typical Performance Characteristics (continued)

Unless otherwise noted: $T_A = 25^\circ\text{C}$, $V_S = 5\text{V}$, $V_{CM} = V_S/2$, $V_{EN} = V^+$.

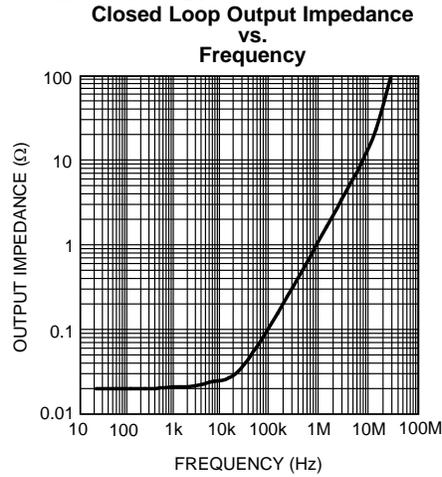


Figure 53.

APPLICATION NOTES

SM73304/SM73305

The SM73304/SM73305 are dual and single, low noise, low offset, rail-to-rail output precision amplifiers with a wide gain bandwidth product of 17 MHz and low supply current. The wide bandwidth makes the SM73304/SM73305 ideal choices for wide-band amplification in portable applications. The low supply current along with the enable feature that is built-in on the SM73304/SM73305 allows for even more power efficient designs by turning the device off when not in use.

The SM73304/SM73305 are superior for sensor applications. The very low input referred voltage noise of only 5.8 nV/ $\sqrt{\text{Hz}}$ at 1 kHz and very low input referred current noise of only 10 fA/ $\sqrt{\text{Hz}}$ mean more signal fidelity and higher signal-to-noise ratio.

The SM73304/SM73305 have a supply voltage range of 1.8V to 5.5V over a wide temperature range of 0°C to 125°C. This is optimal for low voltage commercial applications. For applications where the ambient temperature might be less than 0°C, the SM73304/SM73305 are fully operational at supply voltages of 2.0V to 5.5V over the temperature range of -40°C to 125°C.

The outputs of the SM73304/SM73305 swing within 25 mV of either rail providing maximum dynamic range in applications requiring low supply voltage. The input common mode range of the SM73304/SM73305 extends to 300 mV below ground. This feature enables users to utilize this device in single supply applications.

The use of a very innovative feedback topology has enhanced the current drive capability of the SM73304/SM73305, resulting in sourcing currents as much as 47 mA with a supply voltage of only 1.8V.

The SM73305 is offered in the space saving SOT package and the SM73304 is offered in a 10-pin MSOP. These small packages are ideal solutions for applications requiring minimum PC board footprint.

National Semiconductor is heavily committed to precision amplifiers and the market segments they serves. Technical support and extensive characterization data is available for sensitive applications or applications with a constrained error budget.

CAPACITIVE LOAD

The unity gain follower is the most sensitive configuration to capacitive loading. The combination of a capacitive load placed directly on the output of an amplifier along with the output impedance of the amplifier creates a phase lag which in turn reduces the phase margin of the amplifier. If phase margin is significantly reduced, the response will be either underdamped or the amplifier will oscillate.

The SM73304/SM73305 can directly drive capacitive loads of up to 120 pF without oscillating. To drive heavier capacitive loads, an isolation resistor, R_{ISO} in [Figure 54](#), should be used. This resistor and C_L form a pole and hence delay the phase lag or increase the phase margin of the overall system. The larger the value of R_{ISO} , the more stable the output voltage will be. However, larger values of R_{ISO} result in reduced output swing and reduced output current drive.

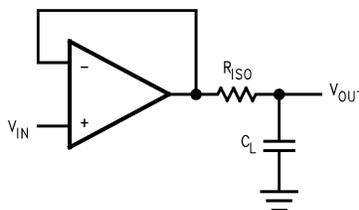


Figure 54. Isolating Capacitive Load

INPUT CAPACITANCE

CMOS input stages inherently have low input bias current and higher input referred voltage noise. The SM73304/SM73305 enhance this performance by having the low input bias current of only 50 fA, as well as, a very low input referred voltage noise of 5.8 nV/ $\sqrt{\text{Hz}}$. In order to achieve this a larger input stage has been used. This larger input stage increases the input capacitance of the SM73304/SM73305. [Figure 55](#) shows typical input common mode input capacitance of the SM73304/SM73305.

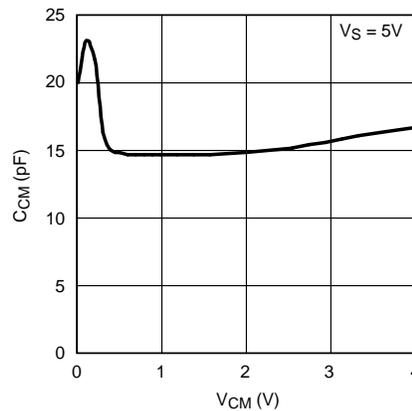


Figure 55. Input Common Mode Capacitance

This input capacitance will interact with other impedances such as gain and feedback resistors, which are seen on the inputs of the amplifier to form a pole. This pole will have little or no effect on the output of the amplifier at low frequencies and under DC conditions, but will play a bigger role as the frequency increases. At higher frequencies, the presence of this pole will decrease phase margin and also causes gain peaking. In order to compensate for the input capacitance, care must be taken in choosing feedback resistors. In addition to being selective in picking values for the feedback resistor, a capacitor can be added to the feedback path to increase stability.

The DC gain of the circuit shown in [Figure 56](#) is simply $-R_2/R_1$.

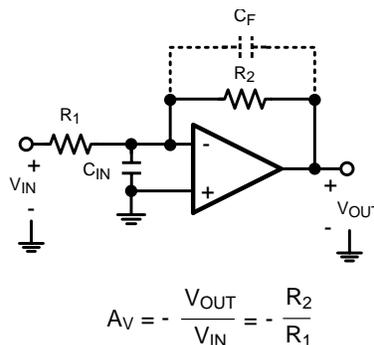


Figure 56. Compensating for Input Capacitance

For the time being, ignore C_F . The AC gain of the circuit in [Figure 56](#) can be calculated as follows:

$$\frac{V_{OUT}}{V_{IN}}(s) = \frac{-R_2/R_1}{\left[1 + \frac{s}{\left(\frac{A_0 R_1}{R_1 + R_2} \right)} + \frac{s^2}{\left(\frac{A_0}{C_{IN} R_2} \right)} \right]} \quad (1)$$

This equation is rearranged to find the location of the two poles:

$$P_{1,2} = \frac{-1}{2C_{IN}} \left[\frac{1}{R_1} + \frac{1}{R_2} \pm \sqrt{\left(\frac{1}{R_1} + \frac{1}{R_2} \right)^2 - \frac{4 A_0 C_{IN}}{R_2}} \right] \quad (2)$$

As shown in [Equation 2](#), as the values of R_1 and R_2 are increased, the magnitude of the poles are reduced, which in turn decreases the bandwidth of the amplifier. [Figure 57](#) shows the frequency response with different value resistors for R_1 and R_2 . Whenever possible, it is best to chose smaller feedback resistors.

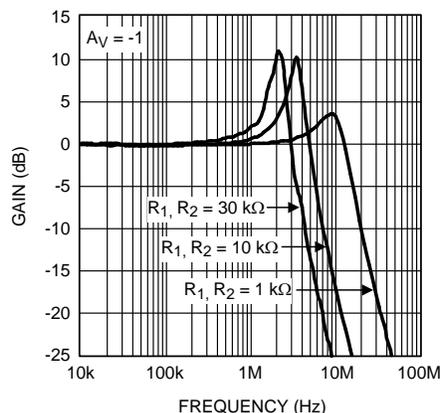


Figure 57. Closed Loop Frequency Response

As mentioned before, adding a capacitor to the feedback path will decrease the peaking. This is because C_F will form yet another pole in the system and will prevent pairs of poles, or complex conjugates from forming. It is the presence of pairs of poles that cause the peaking of gain. Figure 58 shows the frequency response of the schematic presented in Figure 56 with different values of C_F . As can be seen, using a small value capacitor significantly reduces or eliminates the peaking.

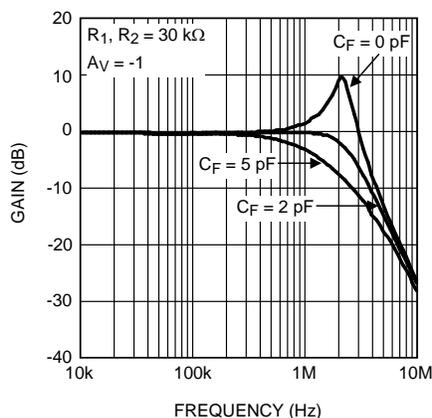


Figure 58. Closed Loop Frequency Response

TRANSIMPEDANCE AMPLIFIER

In many applications, the signal of interest is a very small amount of current that needs to be detected. Current that is transmitted through a photodiode is a good example. Barcode scanners, light meters, fiber optic receivers, and industrial sensors are some typical applications utilizing photodiodes for current detection. This current needs to be amplified before it can be further processed. This amplification is performed using a current-to-voltage converter configuration or transimpedance amplifier. The signal of interest is fed to the inverting input of an op amp with a feedback resistor in the current path. The voltage at the output of this amplifier will be equal to the negative of the input current times the value of the feedback resistor. Figure 59 shows a transimpedance amplifier configuration. C_D represents the photodiode parasitic capacitance and C_{CM} denotes the common-mode capacitance of the amplifier. The presence of all of these capacitances at higher frequencies might lead to less stable topologies at higher frequencies. Care must be taken when designing a transimpedance amplifier to prevent the circuit from oscillating.

With a wide gain bandwidth product, low input bias current and low input voltage and current noise, the SM73304/SM73305 are ideal for wideband transimpedance applications.

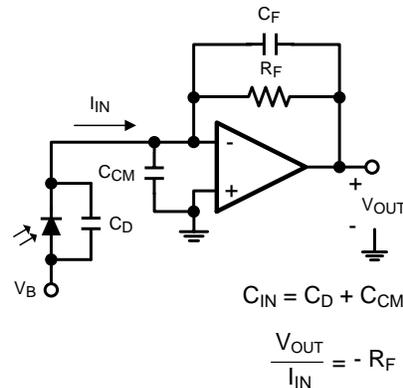


Figure 59. Transimpedance Amplifier

A feedback capacitance C_F is usually added in parallel with R_F to maintain circuit stability and to control the frequency response. To achieve a maximally flat, 2nd order response, R_F and C_F should be chosen by using [Equation 3](#)

$$C_F = \sqrt{\frac{C_{IN}}{GBWP * 2 \pi R_F}} \tag{3}$$

Calculating C_F from [Equation 3](#) can sometimes result in capacitor values which are less than 2 pF. This is especially the case for high speed applications. In these instances, its often more practical to use the circuit shown in [Figure 60](#) in order to allow more sensible choices for C_F . The new feedback capacitor, C'_F , is $(1 + R_B/R_A) C_F$. This relationship holds as long as $R_A \ll R_F$.

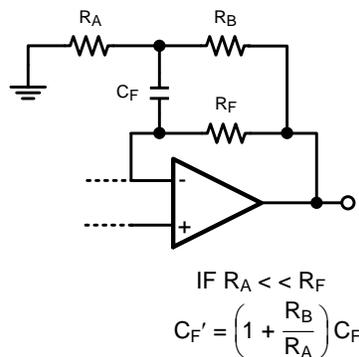


Figure 60. Modified Transimpedance Amplifier

SENSOR INTERFACE

The SM73304/SM73305 have low input bias current and low input referred noise, which make them ideal choices for sensor interfaces such as thermopiles, Infra Red (IR) thermometry, thermocouple amplifiers, and pH electrode buffers.

Thermopiles generate voltage in response to receiving radiation. These voltages are often only a few microvolts. As a result, the operational amplifier used for this application needs to have low offset voltage, low input voltage noise, and low input bias current. [Figure 61](#) shows a thermopile application where the sensor detects radiation from a distance and generates a voltage that is proportional to the intensity of the radiation. The two resistors, R_A and R_B , are selected to provide high gain to amplify this signal, while C_F removes the high frequency noise.

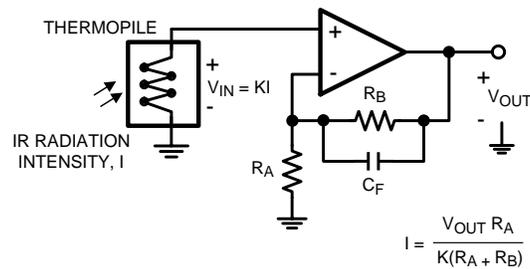


Figure 61. Thermopile Sensor Interface

PRECISION RECTIFIER

Rectifiers are electrical circuits used for converting AC signals to DC signals. [Figure 62](#) shows a full-wave precision rectifier. Each operational amplifier used in this circuit has a diode on its output. This means for the diodes to conduct, the output of the amplifier needs to be positive with respect to ground. If V_{IN} is in its positive half cycle then only the output of the bottom amplifier will be positive. As a result, the diode on the output of the bottom amplifier will conduct and the signal will show at the output of the circuit. If V_{IN} is in its negative half cycle then the output of the top amplifier will be positive, resulting in the diode on the output of the top amplifier conducting and, delivering the signal on the amplifier's output to the circuit's output.

For $R_2/R_1 \geq 2$, the resistor values can be found by using the equation shown in [Figure 62](#). If $R_2/R_1 = 1$, then R_3 should be left open, no resistor needed, and R_4 should simply be shorted.

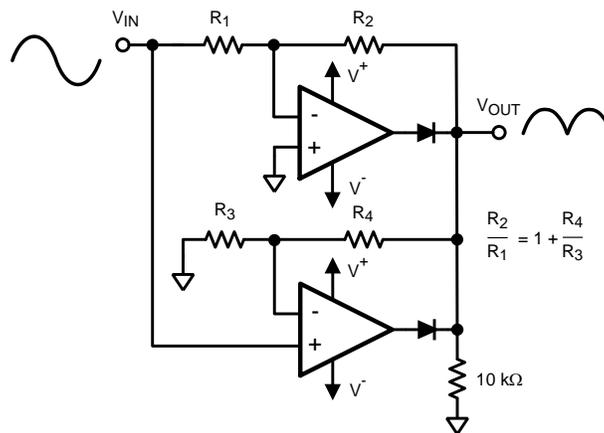


Figure 62. Precision Rectifier

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